



BIJU PATNAIK UNIVERSITY OF TECHNOLOGY,
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Lecture Notes

On

Markov Chain

Part 3

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Markov Chain Part 3

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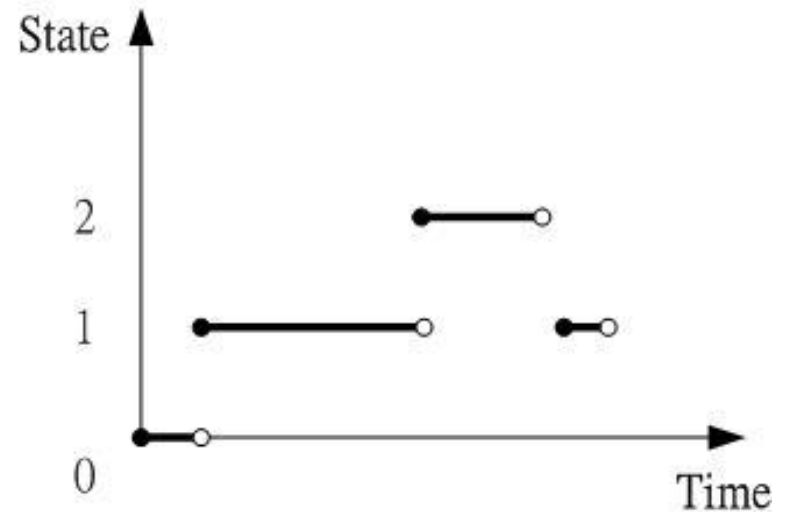
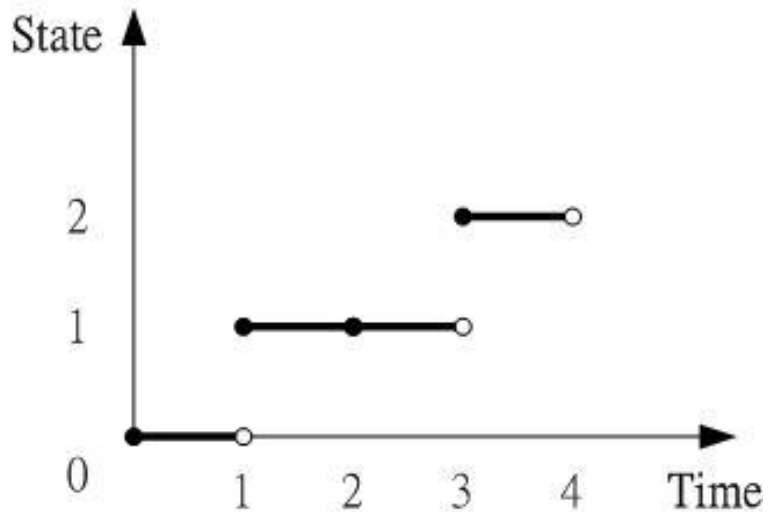


Outline

- Continuous Time Markov Chains
- An Example

Continuous Time Markov Chains

- Discrete Time V.S. Continuous Time





Continuous Time Markov Chains (cont.)

- $X(t')$: the state of the system at time t'
- Three points in time :
 - $t' = r$ is a past time
 - $t' = s$ is the current time
 - $t' = s+t$ is t units of time into the future
- Markovian property :
 - $P\{ X(s+t) = j \mid X(s) = i \text{ and } X(r) = x(r) \} = P\{ X(s+t) = j \mid X(s) = i \}$
for all $i, j = 0, 1, 2, \dots, M$ and for all $r \geq 0, s > r, \text{ and } t > 0$
 - $P\{ X(s+t) = j \mid X(s) = i \}$ is a transition probability.



Continuous Time Markov Chains (cont.)

- Stationary transition probability :
 - If the transition probabilities are independent of s , so that $P\{ X(s+t) = j \mid X(s) = i \} = P\{ X(t) = j \mid X(0) = i \}$ they are called stationary transition probability.
 - $p_{ij}(t) = P\{ X(t) = j \mid X(0) = i \}$ is called the continuous time transition probability function.

- Assumption :
$$\lim_{t \rightarrow 0} p_{ij}(t) = \begin{cases} 1 & \text{if } i = j \\ 0 & \text{if } i \neq j \end{cases}$$



Continuous Time Markov Chains (cont.)

- One key set of random variables, T_i :
 - Each time the process enters state i , the amount of time it spends in that state before moving to a different state. ($i = 0, 1, 2, \dots, M$)
- Memoryless :
 - $P\{ T_i > t + s \mid T_i > s \} = P\{ T_i > t \}$



Continuous Time Markov Chains (cont.)

- An equivalent way of describing a continuous time Markov chain :
 - The random variable T_i has an exponential distribution with a mean $1/q_i$.
 - P_{ij} : the probability of moving from state i to state j .

$$P_{ii} = 0 \text{ and } \sum_{j=0}^M p_{ij} = 1 \text{ for all } i$$

- The next state visited after state i is independent of the time spent in state i .



Continuous Time Markov Chains (cont.)

- Transition rates :

- $q_i = \lim_{t \rightarrow 0} \frac{1 - p_{ii}(t)}{t}$

- $q_{ij} = q_i p_{ij}$

- Steady-state probabilities

- If a Markov chain is irreducible, then $\lim_{t \rightarrow \infty} p_{ij}(t) = \pi_j$

- $\pi_j = \sum_{i=0}^M \pi_i p_{ij}(t)$ for $j = 0, 1, 2, \dots, M$



Continuous Time Markov Chains (cont.)

- Steady-state equation :

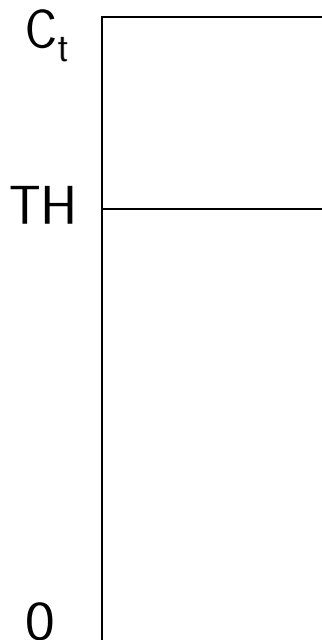
$$\pi_j q_j = \sum_{i \neq j} \pi_i q_{ij} \quad \text{for } j = 0, 1, 2, \dots, M$$

$$\sum_{j=0}^M \pi_j = 1$$



An Example

- Model the traditional guard-channel scheme using continuous time Markov channel.
- The tradition guard-channel scheme :



A new call is admitted only when there are less than TH channels occupied.

A handoff request is rejected only when all channels are occupied.

An Example (cont.)

- The system : A cell
- The state : the number of occupied channels in a cell

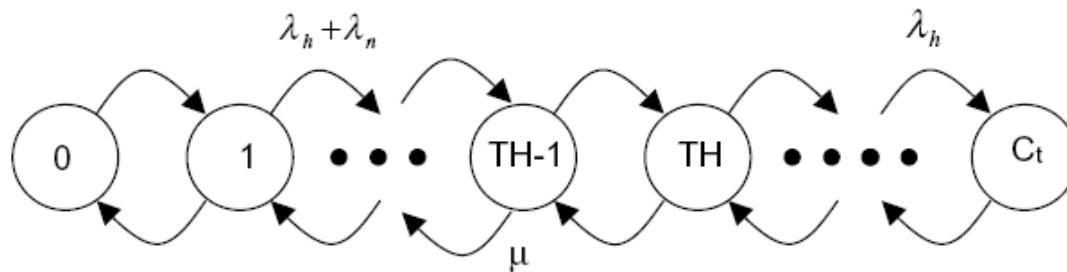


Fig. 2. Markovian model.



An Example (cont.)

- Steady-state probabilities :

$$P_i = \begin{cases} \frac{1}{i!} \left(\frac{\lambda_n + \lambda_h}{\mu} \right)^i p_0, & 0 < i \leq \text{TH} \\ \frac{1}{i!} \left(\frac{\lambda_n + \lambda_h}{\mu} \right)^{\text{TH}} \left(\frac{\lambda_h}{\mu} \right)^{i-\text{TH}} p_0, & \text{TH} < i \leq C_t \end{cases}$$

$$p_0 = \left(\sum_{i=0}^{\text{TH}} \frac{1}{i!} \left(\frac{\lambda_n + \lambda_h}{\mu} \right)^i + \sum_{i=\text{TH}+1}^{C_t} \frac{1}{i!} \left(\frac{\lambda_n + \lambda_h}{\mu} \right)^{\text{TH}} \left(\frac{\lambda_h}{\mu} \right)^{i-\text{TH}} \right)^{-1}$$



An Example (cont.)

- Call dropping probability :

$$P_d = \frac{1}{C_t!} \left(\frac{\lambda_n + \lambda_h}{\mu} \right)^{\text{TH}} \left(\frac{\lambda_h}{\mu} \right)^{C_t - \text{TH}} \cdot \left(\sum_{i=0}^{\text{TH}} \frac{1}{i!} \left(\frac{\lambda_n + \lambda_h}{\mu} \right)^i + \sum_{i=\text{TH}+1}^{C_t} \frac{1}{i!} \left(\frac{\lambda_n + \lambda_h}{\mu} \right)^{\text{TH}} \left(\frac{\lambda_h}{\mu} \right)^{i - \text{TH}} \right)^{-1}$$

- Call blocking probability :

$$P_b = \sum_{i=\text{TH}}^m \frac{1}{i!} \left(\frac{\lambda_n + \lambda_h}{\mu} \right)^{\text{TH}} \left(\frac{\lambda_h}{\mu} \right)^{i - \text{TH}} \cdot \left(\sum_{i=0}^{\text{TH}} \frac{1}{i!} \left(\frac{\lambda_n + \lambda_h}{\mu} \right)^i + \sum_{i=\text{TH}+1}^m \frac{1}{i!} \left(\frac{\lambda_n + \lambda_h}{\mu} \right)^{\text{TH}} \left(\frac{\lambda_h}{\mu} \right)^{i - \text{TH}} \right)^{-1}$$



An Example (cont.)

- Find an TH which guarantees that CDP is kept below the tolerable level.

$$P_d = \frac{1}{C_t!} \left(\frac{\lambda_n + \lambda_h}{\mu} \right)^{TH} \left(\frac{\lambda_h}{\mu} \right)^{C_t - TH} \cdot p_0 \leq P_{td}$$

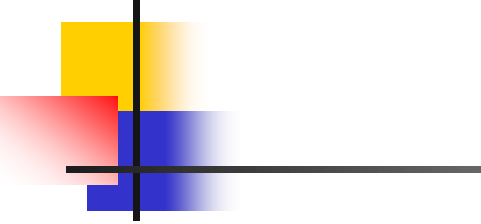
- Why not to keep CBP below the tolerable level ?



An Example (cont.)

- The proposed approach :
 - A cell is classified into two categories, hot cells and cold cells.
 - Hot cells : $C_u > TH$
 - Cold Cells : $C_u \leq TH$
 - Cold cells follow the same CAC as in the traditional guard-channel scheme, while hot cells admit new calls with a probability, PCA, instead of blocking new calls absolutely.

$$PCA(C_u) = \begin{cases} \sin \left(\left(\frac{C_u - TH}{C_t - TH} \right) \cdot \frac{\pi}{2} + \pi \right) + 1, & \text{if } TH \leq C_u \leq C_t \\ 1, & \text{if } C_u < TH \end{cases}$$



```
channel_allocation()
```

```
{
```

```
     $\lambda_h$  = the current arrival rate of handoff call;
```

```
     $\lambda_n$  = the current arrival rate of new call;
```

```
     $y$  = the tolerable dropping rate;
```

```
     $C_t$  = the number of total channels;
```

```
     $C_u$  = the number of occupied channels;
```

```
    TH = the value of threshold such that
```

$$p_d = \frac{1}{C_t!} \left(\frac{\lambda_n + \lambda_h}{\mu} \right)^{TH} \left(\frac{\lambda_h}{\mu} \right)^{C_t - TH} \cdot p_0 \leq p_{td};$$

```
    If (the arriving call is a handoff call)
```

```
        If ( $C_t - C_u > 0$ )
```

```
            Accept this call;
```

```
        Else
```

```
            Drop the handoff call;
```

```
    Else /* new call */
```

```
        If ( $C_u < TH$ )
```

```
            Accept this call;
```

```
        Else
```

$$F = \sin \left(\left(\frac{C_u - TH}{C_t - TH} \right) \cdot \frac{\pi}{2} + \pi \right) + 1;$$

```
         $r = \text{random}()$ ;
```

```
        if ( $r < F$ )
```

```
            Accept this new call;
```

```
        else
```

```
            Block the new call;
```

```
}
```

An Example (cont.)

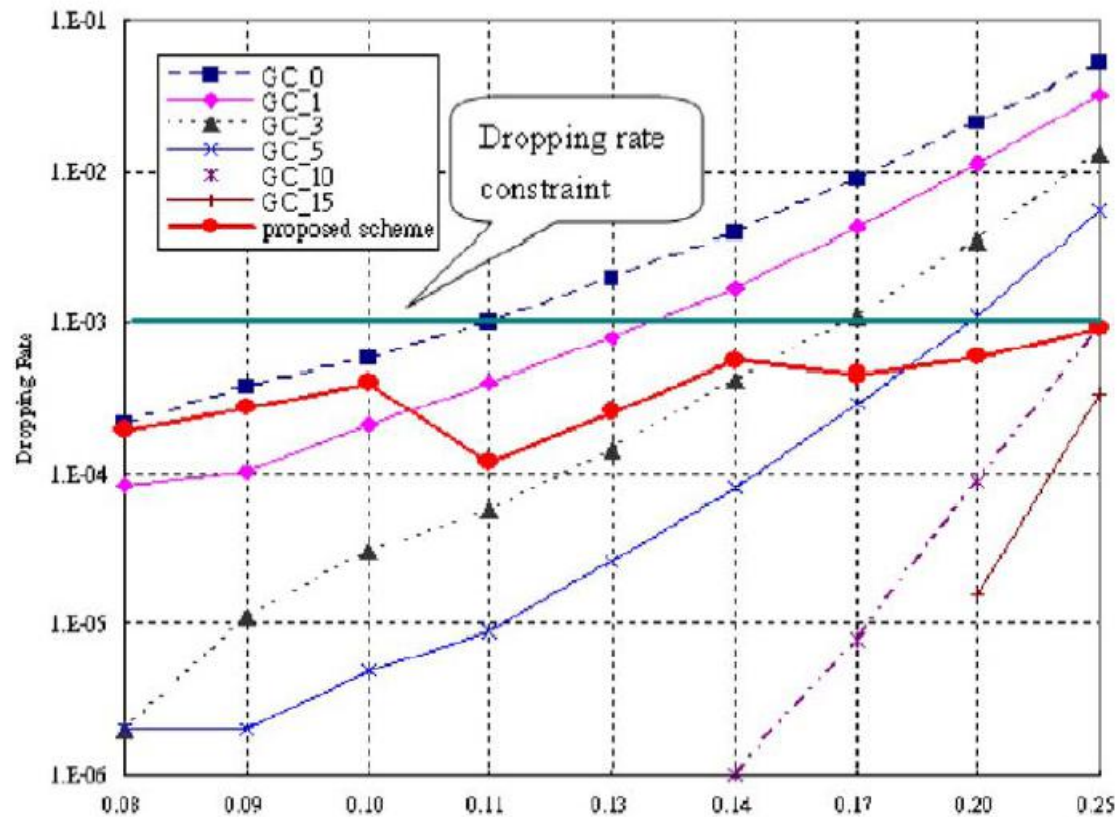


Fig. 4. The dropping rate with different arrival rate of handoff call ($\lambda_n = 1/6$).

An Example (cont.)

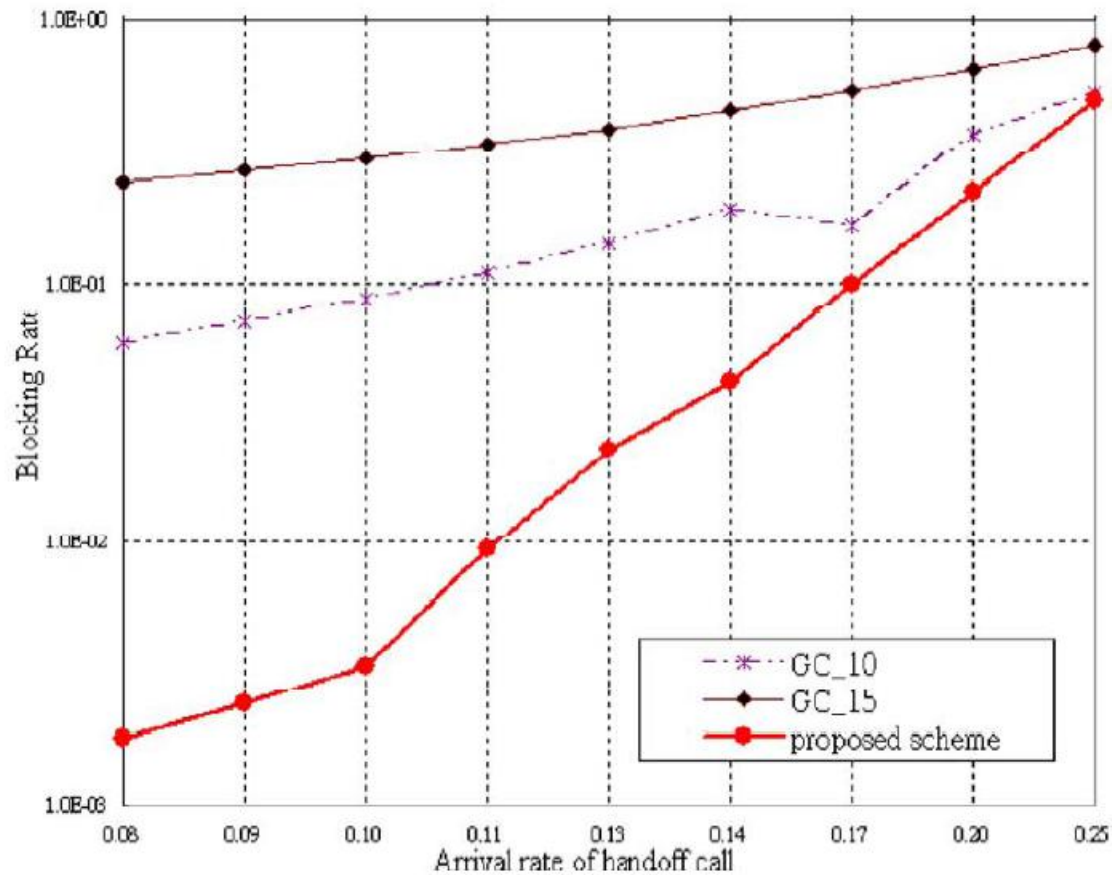


Fig. 5. Blocking rate versus arrival rate of handoff call ($\lambda_n = 1/6$).



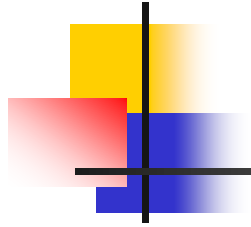
Top Sentences

- **Just as** the transition probabilities for a discrete time Markov chain satisfy the Chapman Kolmogorov equations, the continuous time transition probability function also satisfies these equations.
just as 可用於比擬。 ----- I-Chi
- **More specifically**, a new call request is admitted only when there are less than TH channels occupied.
more specifically 可表示更進一步具體說明。 ----- I-Chi
- We shall **restrict our consideration to** continuous time Markov chains **with the following properties**.
restrict our consideration to 可用於界定討論範圍。 ----- I-Chi



Reference

- *Hillier and Lieberman*, “Introduction to Operations Research”, seventh edition, McGraw Hill
- *Jin-Long Wang and Shu-Yin Chiang*
“Adaptive channel assignment scheme for wireless networks”
Computers and Electrical Engineering



THANK
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